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# **VP160 RECITATION CLASS**

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Notations and Units

Uncertainty and Significant Figures

Back-of-the-envelop Calculations

Vectors

3D curvilinear coordinate systems

**1D** kinematics

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## Notations and Units

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## Notations and Units

#### 1. Scientific Notation

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- 2. Unit Prefix
  - k(unit prefix)m(unit)
  - Some commonly-used unit prefixes:

| р                 | n                | $\mu$            | m                | С                | k               | М               | G               |
|-------------------|------------------|------------------|------------------|------------------|-----------------|-----------------|-----------------|
| 10 <sup>-12</sup> | 10 <sup>-9</sup> | 10 <sup>-6</sup> | 10 <sup>-3</sup> | 10 <sup>-2</sup> | 10 <sup>3</sup> | 10 <sup>6</sup> | 10 <sup>9</sup> |



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3. Basic Units & Derived Units

[m], [kg], [s], [A], [K], [mol], [cd] (S.I. Units)



### Exercise 1

A simple pendulum consists of a light inextensible string AB with length L, with the end A fixed, and a point mass M attached to B. The pendulum oscillates with a small amplitude, and the period of oscillation is T. It is suggested that T is proportional to the product of powers of M, L and g, where g is the acceleration due to gravity. Use dimensional analysis to find this relationship.



# Uncertainty and Significant Figures

### Uncertainty

Because of unavoidavle factors, no measurement can ever be perfect. Its result may therefore only be treated as an estimate of what we call the "exact value" of a physical quantity. The experiment may both overestimate and underestimate the value of the physical quantity, and it is crucial to provide a measure of the error, or better uncertainty, that a result of the experiment carries.

- 1. Type-A Uncertainty
- 2. Type-B Uncertainty



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## Significant Figures

Experimental uncertainty should almost always be rounded to one significant figure. The only exception is when the uncertainty has a leading digit of 1, then we can keep two significant figures.



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## Examples

- 1. 1.7392 (SF=5)
- 2. 0.0970 (SF=3)
- 3. 3.7×10<sup>5</sup> (SF=2)
- 4.  $(9.8\pm0.3)g$
- 5.  $(0.78 \pm 0.12)$ m



## Back-of-the-envelop Calculations

#### Defination

A quick estimation of some physical quantities. You should be able to have an basic idea about the order of magnitude when doing exercises.





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#### Exercise 2

True or False: The power of China Railway High-speed (CRH) is about 500kW.



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## Vectors

#### Defination

Vectors are quantities that have both magnitude and direction.

| Scalar   | Vector       |
|----------|--------------|
| Distance | Displacement |
| Speed    | Velocity     |

Vector in  $R^n$ 

$$\vec{u} = (u_1, u_2, ..., u_n)^T$$



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### Basic vector operations

Addition & Subtraction

$$\vec{u} \pm \vec{v} = (u_1 \pm v_1, u_2 \pm v_2, u_3 \pm v_3)$$

• Scalar Multiplication

$$\lambda \vec{u} = (\lambda u_1, \lambda u_2, \lambda u_3)$$

Dot Product

$$\vec{u} \cdot \vec{v} = |u||v|\cos\theta = u_1v_1 + u_2v_2 + u_3v_3$$



#### Cross Product

- \* Magnitude:  $|\vec{u} \times \vec{v}| = |u||v|sin\theta$
- Direction: determined by Right Hand Rule
- \* Matrix expression:

$$\vec{u} \times \vec{v} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix}$$
$$= (u_2 v_3 - u_3 v_2)\hat{i} + (u_3 v_1 - u_1 v_3)\hat{j} + (u_1 v_2 - u_2 v_i)\hat{k}$$

\* Note that  $(\vec{A} \times \vec{B}) \times \vec{C} \neq \vec{A} \times (\vec{B} \times \vec{C})$ . Why?



## Exercise 3.1

Consider two vectors  $\vec{u} = 3\hat{n_x} + 4\hat{n_y}$ , and  $\vec{w} = 6\hat{n_x} + 16\hat{n_y}$ . Find: (a) the components of the vector  $\vec{w}$  that are parallel and perpendicular to the vector  $\vec{u}$ ,

(b) the angle between  $\vec{w}$  and  $\vec{u}$ .



### Exercise 3.2

Find a vector  $\vec{u}$ , such that:

$$(2\hat{n_x} - 3\hat{n_x} + 4\hat{n_x}) \times \vec{u} = 4\hat{n_x} + 3\hat{n_x} - \hat{n_x}$$

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#### Exercise 3.3

Check that in Cartesian coordinates, the two expression equations of dot product of two vectors  $\vec{u}$  and  $\vec{v}$  are equivalent:

$$\vec{u} \cdot \vec{v} = u_1 v_1 + u_2 v_2 + u_3 v_3$$
$$\vec{u} \cdot \vec{v} = |u| |v| \cos\theta$$



## 3D curvilinear coordinate systems

### Cartesian Coordinate

- 1. Coordinates: *x*, *y*, *z*
- 2. Unit vectors:  $\hat{n}_x, \hat{n}_y, \hat{n}_z$
- 3. Position vector:  $\vec{r} = x\hat{n_x} + y\hat{n_y} + z\hat{n_z}$



### Cylindrical Coordinate

- **1.** Coordinates:  $\rho, \phi, z$
- **2**. Unit vectors:  $\hat{n}_{\rho}, \hat{n}_{\phi}, \hat{n}_{z}$
- **3**. Position vector:  $\vec{r} = \rho \hat{n_{\rho}} + z \hat{n_{z}}$
- 4. Relationship with Cartesian Coordinate:

$$\begin{cases} \rho = \sqrt{x^2 + y^2} \\ \phi = \arctan(y/x) \\ z = z \end{cases} \qquad \begin{cases} x = \rho \cos(\theta) \\ y = \rho \sin(\phi) \\ z = z \end{cases}$$



#### Spherical Coordinate

- **1**. Coordinates:  $r, \phi, \theta$
- 2. Unit vectors:  $\hat{n}_r, \hat{n}_{\phi}, \hat{n}_{\theta}$
- 3. Position vector:  $\vec{r} = r\hat{n_r}$
- 4. Relationship with Cartesian Coordinate:

$$\begin{cases} r = \sqrt{x^2 + y^2 + z^2} \\ \phi = \arctan(y/x) \\ \theta = \arctan(\sqrt{x^2 + y^2}/z) \end{cases} \begin{cases} x = \rho \sin(\theta) \cos(\phi) \\ y = r\sin(\theta) \sin(\phi) \\ z = r\cos(\theta) \end{cases}$$



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### Exercise 4 Derive the above relation equations.



## **1D** kinematics

## **Differential Equations**

$$x = x(t)$$

$$v = v(t) = \frac{d}{dt}x(t)$$

$$a = a(t) = \frac{d}{dt}v(t) = \frac{d^2}{dt^2}x(t)$$

### **Relative Motion**

$$x = x_r + x';$$
  $v = v_r + v';$   $a = a_r + a'$ 

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### Exercise 5.1

A particle moves along a straight line with non-constant acceleration  $a_x(t) = -A\omega^2 \cos\omega t$ , where *A* and  $\omega$  are positive constants. At the instant of time t = 0 its velocity  $v_x(0) = 3$  [m/s] and position x(0) = 4 [m]. (a)What are the units of these constants? (b)Find  $v_x(t)$  and x(t) at any instant of time. (c)Sketch the graphs of x(t),  $v_x(t)$ , and  $a_x(t)$ . (d)What kind of motion may these results describe?



### Exercise 5.2

A particle is moving along a straight line with velocity  $v_x(t) = -\beta A\omega e^{-\beta} \cos \omega t$ , where *A*,  $\omega$ , and  $\beta$  are positive constants. Assuming that x(0) = 5[m].

(a)What are the units of these constants?

(b)Find acceleration  $a_x(t)$  and position x(t) of the particle.

(c)Sketch the graphs of x(t),  $v_x(t)$ , and  $a_x(t)$ .

(d)What kind of motion may these results describe?



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### Exercise 5.3

A car is moving in one direction along a straight line. Find the average velocity of the car if:

(a) it travels half of the journey time with velocity  $v_1$  and the other half with velocity  $v_2$ ,

(b) it covers half of the distance with velocity  $v_1$  and the other one with velocity  $v_2$ .



#### Exercise 5.4

In a certain motion of a particle along a straight line, the acceleration turns out to be related to the position of the particle according to the formula  $a_x = \sqrt{kx}$ , where k > 0 is a constant and x > 0. How does the velocity depend on x, if we know that for  $v_x(x_0) = v_0$ ?



### Exercise 5.5

A dripping water faucet steadily releases frops 1.0s apart. As these drops fall, does the distance between them decrease, increase, or remain the same?(Try to find the answer without calculation)

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### Exercise 5.6

A spare paddle drops from a fisherman's canoe. After one hour of paddling the fisherman realizes that the paddle is missing. He turn around and paddles his canoe back to find the paddle. Assume that the fisherman paddles always with the same speed v = 10 km/h with respect to the river, the speed of the rivers current is u = 6km/h. Find:

(a) the time that the fisherman takes to find the paddle;

(b)the distance between the places where the paddle drops and the fisherman find it.

Can you find the answers in a second?